Obliczenie azymutu i długości ze współrzędnych

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| L.p. | Oznaczenia  punktów: *B*  *A* | *XB* | *YB* | tg *ϕ*= | cos *ϕ* | Kontrola | |
| Δ*x*+Δ*y* | *ψ* |
| *XA* | *YA* | Czwartak *ϕ* | sin *ϕ* | Δ*x*–Δ*y* | *A*+45° (50g)° |
| Oznaczenie  zwrotu  boku: *A*→*B* | Δ*xAB = XB – XA* | Δ*yAB = YB – YA* | **Azymut*AAB*** | **Odległość** |  |  |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| *1* |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
| *2* |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |